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The Solution of Fuzzy Integral Equation by Using Sinc Collocation Method

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Author's contribution

The sole author designed, analyzed, interpreted and prepared the manuscript.

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Original Research Article

Abstract

The present paper recommends a new approach to solve a fuzzy integral equation. In this work, our main purpose is finding an approximate solution of this problem by using Sinc-collocation method. We first present some properties of the Sinc-collocation method required for our work, then some basic concepts and necessary materials of fuzzy numbers are expressed in the third part of this paper. In the next section, we apply our method for fuzzy integral equation and show that the approximate solution converges to the exact solution at an exponential rate. Numerical examples given in the last part confirm the accuracy and validity of our new technique. In this example, we obtain the Hausdorff distance between exact solution and approximate solution.

Keywords: Fuzzy integral equations; Sinc-collocation methods; Hilbert space; Conformal map; Whittakers cardinal function.

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1 Introduction

This paper is concerned with a numerical solution of fuzzy Fredholm integral equation. The concept of fuzzy integral equations has been considered by various authors and has been developed rapidly. Ralescu and Adams in [1] presented fuzzy integral of a positive measurable function with respect to a fuzzy measure. They showed that the monotone convergence theorem and Fatous lemma are true in new setting. In 1982, Dubois and Prade published a paper in which they investigated the concept of integration of fuzzy functions. In this paper, they define the integral of such fuzzy mappings over a crisp interval and provide a special analytical representation of fuzzy mapping [2]. In [3], the auto-continuity of a set function and Sugeno's fuzzy measure with some conditions are introduced by Wang. He proved Egoroffs theorem on a fuzzy measure space and some convergence theorems of sequence of fuzzy integrals. Goetschel and Voxman defined differentiation and integration of fuzzyvalued functions by using the usual vector space operations with a spatial metric in [4]. Nanda in [5] generalized the integral introduced by Matloka [6] and also extended Riemann-Stieltjes integral over a closed interval to fuzzy mappings. However, several attempts have been made to apply numerical methods to solve fuzzy integral equations. These techniques have been rapidly developed in recent years. The interested reader can see [7, 8, 9, 10, 11] for some more provided methods to solve fuzzy integral equations. In the present paper, we apply Sinc-collocation method to solve fuzzy Fredholm integral equations. Sinc-collocation method is one of the new and powerful techniques which gives fast and accurate solutions. Sinc-collocation method developed by Frank Stenger, [12, 13, 14], Lund [15] and other authors [16, 17, 18, 19]. In recent years, some authors have been tried to generalized the concept of Sinc methods to fractional calculus. In [20], Fractional integrals, fractional derivatives, fractional integral equations, and fractional differential equations are numerically solved by Sinc methods. For more information about fractional calculus you can see [21, 22, 23, 24, 25, 26, 27]. In this study, we first introduce the Sinc function with its properties and then we state some properties and definitions of fuzzy numbers. However, we apply Sinc collocation method to solve fuzzy Fredholm integral equation. Finally, the efficiency and accuracy of this method is shown by some examples.

2 Definitions and Basic Results

Let C denote the set of complex numbers. A function f is analytic at $z_0 \in C$ if its derivative exists at each point in some neighborhood of z_0 . If f is analytic in all of C, then f is called entire.

Definition 2.1. The following function defined for all $z \in C$ is called the Sinc function (See Fig. 1).

$$\operatorname{Sinc}(z) = \begin{cases} \frac{\sin(\pi z)}{\pi z} & z \neq 0, \\ 1 & z = 0. \end{cases}$$
(2.1)

Obviously, this is an entire function and arises frequently in the theory of Fourier transforms. Let f be a real function and h be a positive integer. Set

$$S(k,h) = \operatorname{Sinc}\left(\frac{x-kh}{h}\right), \quad k = 0, \pm 1, \pm 2, \dots$$

The series $\sum_{k=-\infty}^{\infty} f(kh)S(k,h)$ is called the cardinal series of function f with respect to the integer h. If this series converges, its sum is denoted by C(f,h)(x) and is called Whittaker cardinal function of f. Note that this function was first studied by E. T. Whittaker [28]. The Cardinal function of f is given by

$$C(f,h)(x) = \sum_{k=-\infty}^{\infty} f(kh)S(k,h).$$
(2.2)

Clearly, the cardinal function interpolates f at the points $\{kh\}_{k=-\infty}^{\infty}$. This function appears in various and extensive areas. Stenger in [14] applied cardinal function to derive new approximations for interpolating, integrating and approximating the Fourier series over $(-\infty, \infty)$ and Hilbert transforms over $(-\infty, \infty)$, $(0, \infty)$ and (-1, 1). Moreover, this function is used to approximate the derivations of functions over $(-\infty, \infty)$, $(0, \infty)$ and (-1, 1) [29].



Fig. 1. The graph of a Sinc function

Let h be a positive constant. Let B(h) denote the set of all entire functions f such that

$$|f(z)| \le K \exp(\frac{\pi |z|}{h})$$
 and $\left\{ \int_a^b |f(x)|^2 dx \right\}^{1/2} < \infty$

for some constant K > 0. Let us recall an important theorem from [30] showing that when a function is approximated by cardinal series.

Theorem 2.1. If $f \in B(h)$, then for all $z \in C$

$$f(z) = C(f,h)(z) = \sum_{k=-\infty}^{\infty} f(kh) \operatorname{Sinc}(\frac{z-kh}{h}).$$

Definition 2.2. Let f be analytic in a domain D and $z_0 \in D$. Then f is called conformal at z_0 if $f'(z_0) \neq 0$. If $f'(z_0) \neq 0$ for all points in domain D, then f is called a conformal mapping of D.

 $Remark\ 2.1.$ The following statements are satisfied:

- 1. If function f is conformal, then it preserves angles.
- 2. If $f: D \to C$ is conformal and one-to-one, then f^{-1} is conformal where f^{-1} is the inverse of f.
- 3. If $f: D \to C$ and $g: C \to C$ are conformal maps, then gof(z) = g(f(z)) is also a conformal map of z.

The following linear fractional transformation is a specific class of conformal maps of $\mathcal{C}\setminus\{-d/c\}$ onto $\mathcal{C}\cup\{\infty\}$

$$L(z) = \frac{az+b}{cz+d}, \qquad ad-bc \neq 0,$$

since L(z) is analytic on $\mathcal{C}\setminus\{-d/c\}$ and $L^{'}(z) \neq 0$, for all $z \in \mathcal{C}\setminus\{-d/c\}$. However, with regard to Remak (2.1) the following map

$$\varphi oL : \mathcal{D}_W \to \mathcal{D}_S$$

 $\varphi(L(z)) = \ln(\frac{az+b}{cz+d})$

is conformal, where

$$\mathcal{D}_W = \{ z \in \mathcal{C} \mid \arg(\frac{az+b}{cz+b}) < d \},$$

$$\mathcal{D}_S = \{ w \in \mathcal{C} \mid w = x + iy, \ |Img(w)| < d \}.$$

Definition 2.3. Two domains D and W are called conformally equivalent if there exists a conformal one to one map φ of D onto W.

In the following, let us introduce some basic concepts of Sinc approximation. Let φ be a conformal one to one map of a simply connected domain \mathcal{D} onto

$$\mathcal{D}_{S} = \{ x + iy : |y| \le d \}, \tag{2.3}$$

where d is a positive constant. Let us denote the boundary of \mathcal{D} by $\partial \mathcal{D}$. Let a, b be two distinct points of $\partial \mathcal{D}$ and assume that $\varphi(a) = -\infty$ and $\varphi(b) = \infty$. Denote the inverse function φ^{-1} by ψ and let Γ be defined by $\Gamma = \{z \in \mathcal{C} \mid z = \psi(x) , x \in R\} = \psi(R)$. For h > 0, let us define the Sinc points z_k by $z_k = \psi(kh), k = 0, \pm 1, \pm 2, \ldots$ Note that the domains \mathcal{D} and \mathcal{D}_S are conformally equivalent. In this research, the approximation of a function is studied by using a finite number of terms of (2.2). In 1949, Goodwin [31] discovered that the accuracy of the approximation of series (2.2) will increase for those functions which are analytic in the strip $\mathcal{D}_S = \{x + iy : |y| \le d\}$ and converge rapidly to zero as $x \to \pm \infty$.

Now let us give an important class of functions applied in quadrature rule. Let $B(\mathcal{D}_W)$ denote the family of functions F which are analytic in \mathcal{D}_W and satisfy

$$\int_{\psi(u+L)} |F(z)dz| \to 0, \quad u \to \pm \infty,$$

where $L = \{iv : |v| < d \leq \frac{\pi}{2}\}$ and on the boundary of \mathcal{D}_W (denoted by $\partial \mathcal{D}_W$) satisfy

$$\mathcal{N}(F) \equiv \int_{\partial \mathcal{D}_W} |F(z)dz| < \infty.$$

In the what follows, we introduce the Sinc trapezoidal quadrature rule from [15]. This rule which is stated in the next corollary, is very important in our research.

Corollary 2.2. [32] Let $F \in B(\mathcal{D}_W)$ and φ be a conformal map with constants α and C such that

$$\left|\frac{F(z)}{\varphi'(z)}\right| \le C \ e^{-\alpha|\varphi(z)|}, \quad z \in \Gamma,$$

then by selecting $h = \sqrt{\pi d/\alpha N}$ the Sinc trapezoidal quadrature rule is expressed as below

$$\int_{\Gamma} F(z)S(k,h)o\phi(z)dz = h\frac{F(z_k)}{\phi'(z_k)} + O(\exp(-(2\pi d\alpha N)^{\frac{1}{2}})).$$
(2.4)

3 Fuzzy Set Properties

A nonempty subset B of R is called fuzzy convex if and only if $u(\lambda x + (1 - \lambda)y) \ge min\{u(x), u(y)\}$, for every $x, y \in B$ and $\lambda \in [0, 1]$. Let $H(R^n)$ denote the space of non-empty compact convex subsets of R^n . Recall that for any $A \subseteq H(R^n)$ we define

$$d(x,A) = \inf_{a \in A} d(x,a)$$

to be the distance of any $x \in \mathbb{R}^n$ from A, and for any positive number ε , we define the ε -neighborhood of A as the set

$$N(A,\varepsilon) = \left\{ x \in \mathbb{R}^n | \ d(x,A) < \varepsilon \right\} = \bigcup_{a \in A} \left\{ x \in \mathbb{R}^n | \ d(x,a) < \varepsilon \right\}.$$

Notice that the infimum in the definition of d(x, A) is actually achieved, that is, there is a point $a \in A$ such that d(x, A) = d(x, a), because A is compact. For A and $B \in H(\mathbb{R}^n)$, the Hausdorff separation $\rho(A, B)$ is defined as below

$$\rho(A, B) = \inf \{ \varepsilon > 0 | A \subseteq N(B, \varepsilon) \}.$$

The Hausdorff metric on $H(\mathbb{R}^n)$ is introduced as below

$$d_H(A, B) = \max \{ \rho(A, B), \rho(B, A) \}$$

= inf {\varepsilon | A \sum N(B, \varepsilon) and B \sum N(A, \varepsilon) \}.

It is obvious that $(H(\mathbb{R}^n), d_H)$ is a complete and separable metric space [33].

Definition 3.1. A fuzzy number is a function such as $u : \mathbb{R}^n \to [0, 1]$ satisfying the following properties:

- 1. u is normal, i.e. $\exists x_0 \in \mathbb{R}^n$ such that $u(x_0) = 1$,
- 2. u is fuzzy convex,
- 3. u is upper semicontinuous,
- 4. $[u]^0 = \overline{\{x \in R^n : u(x) > 0\}}$ is compact.

The set of all fuzzy numbers is denoted by E^n . If u is a fuzzy number in \mathbb{R}^n , we define $[u]^{\alpha} = \{x \in \mathbb{R}^n \mid u(x) > \alpha\}$ the α -level of u with $0 < \alpha \leq 1$. For $\alpha = 0$ the support of u is defined as $[u]^0 = supp(u) = \{x \in \mathbb{R}^n \mid u(x) > 0\}$. Clearly, for any $\alpha \in [0, 1]$, $[u]^{\alpha}$ is a bounded closed interval. For all $u, v \in \mathbb{E}^n$ and for any real number λ we obtain

$$[u+v]^{\alpha} = [u]^{\alpha} + [v]^{\alpha} \quad , \quad [\lambda u]^{\alpha} = \lambda [u]^{\alpha}, \qquad \forall \alpha \in [0,1].$$

In the what follows, we present another definition for a fuzzy number which will be used in the rest of this paper.

Definition 3.2. An arbitrary fuzzy number is showed by an ordered pair of functions $(\underline{u}(r), \overline{u}(r)), 0 \le r \le 1$, which satisfies the following requirements:

- 1. $\underline{u}(r)$ is a bounded left semicontinuous non-decreasing function over [0, 1],
- 2. $\overline{u}(r)$ is a bounded left semicontinuous non-increasing function over [0, 1],
- 3. $\underline{u}(r) \leq \overline{u}(r), \ 0 \leq r \leq 1.$

In particular, if \underline{u} , \overline{u} are linear functions we have a triangular fuzzy number. A crisp number u is simply represented by $\underline{u}(r) = \overline{u}(r) = u$, $0 \leq r \leq 1$. For arbitrary fuzzy numbers $u = (\underline{u}(r), \overline{u}(r))$, $v = (\underline{v}(r), \overline{v}(r))$ we have the following algebraic operations:

- $1. \ ku = \left\{ \begin{array}{ll} (k\underline{u},k\overline{u}) & k \geq 0, \\ (k\overline{u},k\underline{u}) & k < 0, \end{array} \right.$
- 2. $u + v = (\underline{u}(r) + \underline{v}(r), \overline{u}(r) + \overline{v}(r)),$
- 3. $u v = (u(r) \overline{v}(r), \overline{u}(r) v(r)).$

We now introduce the concepts of fuzzy Differentiability and integrability. Two following definitions are due to Puri and Ralesco in [34] and R. Goetschel and W. Voxman in [4].

Definition 3.3. A fuzzy function $F: (a, b) \to \mathbb{R}^n$ is called differentiable at $t_0 \in (a, b)$ if there exists $F'(x_0) \in \mathbb{R}^n$, such that the limits

$$\lim_{h \to 0^+} \frac{F(t_0 + h) - F(t_0)}{h} \text{ and } \lim_{h \to 0^+} \frac{F(t_0) - F(t_0 - h)}{h}$$

both exist and are equal to $F'(x_0)$.

Definition 3.4. Let $f : [a, b] \to E^1$ be a fuzzy function. For each partition $P = \{t_0, t_1, \ldots, t_n\}$ of [a, b] with $\Delta = \max_{i=1,\ldots,n} |t_i - t_{i-1}|$ and for arbitrary $\xi_i \in [t_{i-1}, t_i]$ $(i = 1, \ldots, n)$, set

$$R_P = \sum_{i=1}^{N} f(\xi_i)(t_i - t_{i-1}).$$

The definite integral of f over [a, b] is defined as below

$$\int_{a}^{b} f(t)dt = \lim_{\Delta \to 0} R_{P}$$

If the fuzzy function f is continuous in the metric D, then this integral exists. Furthermore,

$$\overline{\int_{a}^{b} f(t,r) dt} = \int_{a}^{b} \overline{f}(t,r) dt,$$
$$\underline{\int_{a}^{b} f(t,r) dt} = \int_{a}^{b} \underline{f}(t,r) dt.$$

Note that the definition of fuzzy Riemann integral is stated here. The interested reader can refer to [1] for definitions and some properties of fuzzy Lebesgue integral, you can also see the fuzzy integral of a positive, measurable function with respect to a fuzzy measure, the monotone convergence theorem and Fatous lemma in the space of fuzzy number.

4 **Fuzzy Fredholm Integral Equations**

In this section, we want to solve the following fuzzy integral equations

$$\widetilde{u}(x) = \widetilde{g}(x) + \lambda \int_{a}^{b} k(x,t)\widetilde{u}(t)dt, \qquad (4.1)$$

where $\lambda > 0$ and k(x,t) is an arbitrary kernel function over the square $a \leq x, t \leq b$ and $\tilde{g}(x)$ is a fuzzy function of x. Let $\widetilde{u}(x)$ is an unknown fuzzy function in the space C[a, b] of continuous functions on the closed interval [a, b]. We now introduce parametric form of Equation (4.1) as follows:

$$\underline{u}(x,r) = \underline{g}(x,r) + \begin{cases} \int_a^b k(x,t)\underline{u}(t,r)dt & k(x,t) > 0\\ \int_a^b k(x,t)\overline{u}(t,r)dt & k(x,t) < 0 \end{cases}$$

$$\overline{u}(x,r) = \overline{g}(x,r) + \begin{cases} \int_a^b k(x,t)\overline{u}(t,r)dt & k(x,t) > 0\\ \int_a^b k(x,t)\underline{u}(t,r)dt & k(x,t) < 0 \end{cases}$$

for each $0 \le r \le 1$ and $a \le x, t \le b$. For solving these integral equations we apply Sinc-collocation method. Let φ be a conformal map on the interval (a, b). Consider the following basic functions on C

$$\chi_k(x) = S(k,h)o\varphi(x)$$

= sinc $\left(\frac{\varphi(x) - kh}{h}\right), \quad k \in \mathbb{Z}.$

Obviously, $\{\chi_k\}_{k=1}^{\infty}$ is a dense linearly independent set in \mathcal{C} , set $H_N = span\{\chi_1, \ldots, \chi_N\}$. However, each function $\widetilde{u} \in H_N$ is approximated by

$$\widetilde{u}_m(x) = \sum_{k=-M}^{N} \widetilde{u}_k \chi_k(x), \qquad m = M + N + 1,$$

where N is a positive integer number and the coefficients \tilde{u}_k should be determined. Therefore, in Equation (4.1), all functions are approximated as below

$$\begin{split} \widetilde{u}(x) &= \sum_{j=-N}^{N} \widetilde{u}_{j} S(j,h) o\varphi(x), \\ k(x,t) &= \sum_{j=-N}^{N} \sum_{i=-N}^{N} k_{j,i} S(j,h) o\varphi(x) S(i,h) o\varphi(t), \\ \widetilde{g}(x) &= \sum_{j=-N}^{N} \widetilde{g}_{j} S(j,h) o\varphi(x). \end{split}$$

By substituting these functions in Equation (4.1), we obtain

$$\sum_{j=-N}^{N} \widetilde{u}_{j}S(j,h)o\varphi(x) = \sum_{j=-N}^{N} \widetilde{g}_{j}S(j,h)o\varphi(x) + \int_{0}^{1} \sum_{j=-N}^{N} \sum_{i=-N}^{N} k_{j,i}P_{i}S(j,h)o\varphi(x)S(i,h)o\varphi(t)dt.$$

Using Equation (2.4), we have

$$\sum_{j=-N}^{N} \left[\widetilde{u}_j - \sum_{i=-N}^{N} h \frac{k_{ji}}{\varphi'_i} \right] S(j,h) o\varphi(x) = \sum_{j=-N}^{N} \widetilde{g}_j S(j,h) o\varphi(x)$$

These equations can be simplified in the matrix form as bellow:

$$\widetilde{U} - K = \widetilde{G},\tag{4.2}$$

where

$$\widetilde{U} = \begin{pmatrix} \widetilde{u}_N \\ \vdots \\ \widetilde{u}_{-N} \end{pmatrix} , \quad \widetilde{G} = \begin{pmatrix} \widetilde{g}_N \\ \vdots \\ \widetilde{g}_{-N} \end{pmatrix}$$

and $K = \begin{bmatrix} \frac{k_{j_i}}{\varphi_i} \end{bmatrix}$ is a square matrix of order $(2N+1) \times (2N+1)$. The system (4.2) provides a set of 2N+1 equations which can be calculated for the unknown coefficients $(\widetilde{u}_{-N}, \ldots, \widetilde{u}_N)$.

5 Numerical Results

At this stage, we need to select a conformal map and use it to find the Sinc grid points. In this research, we consider the conformal map

$$\varphi(z) = \ln\left(\frac{z}{1-z}\right) \tag{5.1}$$

which maps the region

$$\mathcal{D}_W = \left\{ z \in \mathcal{C} \mid \arg\left(\frac{z}{1-z}\right) < d \right\}$$

onto the infinite strip \mathcal{D}_S defined in (2.3). The function

$$z=\varphi^{-1}(w)=\frac{e^w}{1+e^w}$$

is an inverse mapping of $w = \varphi(z)$. The range of $\psi = \varphi^{-1}$ on the real line is defined as

$$\Gamma = \left\{ \psi(u) = \varphi^{-1}(u) \in \mathcal{D}_W \mid u \in R \right\} = (0, 1).$$

The Sinc grid points $z_k \in (0, 1)$ in \mathcal{D}_W will be denoted by x_k because they are real. As mentioned in Section 2, these nodes are obtained by

$$x_k = \varphi^{-1}(kh) = \frac{e^{kh}}{1 + e^{kh}}.$$

In the following, let us present some fuzzy integral equations to show the efficiency of the method proposed in the previous sections. In the next examples, put $\alpha = 1/2$ and $d = \pi/2$ which leads to $h = \pi/\sqrt{N}$.



Fig. 2. The exact and approximate solutions

Example 5.1. Consider the following integral equation

$$\widetilde{u}(x,r) = \widetilde{g}(x,r) + \int_0^{\pi/2} (x+t)\widetilde{u}(t,r)dt,$$

where

$$\underline{g}(x,r) = (r^2 - 2r + 2)(\sin x - x - 1),$$

$$\overline{g}(x,r) = (\sin \frac{\pi r}{6} + \frac{r}{2})(\sin x - x - 1).$$

The exact solution in this case is given by

$$\underline{u}(x,r) = (r^2 - 2r + 2)\sin x$$

$$\overline{u}(x,r) = (\sin\frac{\pi r}{6} + \frac{r}{2})\sin x$$

see Fig. 2.

Example 5.2. Consider the following integral equation

$$\widetilde{u}(x,r) = \widetilde{g}(x,r) + \int_0^1 e^{x^2 + t} \ \widetilde{u}(t,r) dt,$$

where

$$\underline{g}(x,r) = (-r^2 + 2)(x + 1 - e^{x^2 + 1}),$$

$$\overline{g}(x,r) = \frac{1}{2}(\sin^2 \frac{\pi r}{2} + 1)[1 - 2x^2 - (3 - e)e^{x^2}].$$

 $The \ exact \ solution \ of \ the \ above \ equation \ is$

$$\underline{u}(x,r) = (-r^2 + 2)(x+1), \overline{u}(x,r) = \frac{1}{2}(\sin^2\frac{\pi r}{2} + 1)(1 - 2x^2)$$





Fig. 3. The exact and approximate solutions

6 Conclusions

The purpose of the current study is to apply the Sinc-collocation method for solving fuzzy Fredholm integral equation. This method is based on Sinc basis functions. The main advantage of this method is that the order of convergence is at an exponential rate. However, properties of Sinc-collocation method have been employed to transform fuzzy integral equation to an explicit form of algebraic equations which is easy to accomplish. The numerical examples in the last section verify the efficiency of our procedure.

Competing Interests

Author has declared that no competing interests exist.

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