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Generating stable molecules using imitation and reinforcement learning

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Abstract

Chemical space is routinely explored by machine learning methods to discover interesting molecules, before time-consuming experimental synthesizing is attempted. However, these methods often rely on a graph representation, ignoring 3D information necessary for determining the stability of the molecules. We propose a reinforcement learning (RL) approach for generating molecules in Cartesian coordinates allowing for quantum chemical prediction of the stability. To improve sample-efficiency we learn basic chemical rules from imitation learning (IL) on the GDB-11 database to create an initial model applicable for all stoichiometries. We then deploy multiple copies of the model conditioned on a specific stoichiometry in a RL setting. The models correctly identify low energy molecules in the database and produce novel isomers not found in the training set. Finally, we apply the model to larger molecules to show how RL further refines the IL model in domains far from the training data.

1. Introduction

Discovering novel molecules or materials with desirable properties is a challenging task because of the immense size of chemical compound space. Further complicating the process is the costly and time-consuming process of synthesizing and testing proposed structures. Whereas this procedure historically was driven by a trial-and-error process, the advance of computational quantum chemical methods allows for initial screening to select promising molecules for experimental testing. While the computational resource growth provided a significant speed-up in processing molecules an exhaustive search of molecular compound space is still infeasible. Instead an automated search for interesting candidates is desired. Examples of such search methods include evolutionary algorithms[[1](#page-17-0), [2\]](#page-17-1), basin-hopping[[3\]](#page-17-2) and particle swarm optimization[[4\]](#page-17-3).

More recently, machine learning (ML) enhanced versions of aforementioned methods [\[5](#page-17-4)[–7\]](#page-17-5) and regression methods facilitating speed-up of virtual screening [\[8](#page-17-6), [9\]](#page-17-7) have gained considerable interest by making researchers able to quickly identify attractive candidates for experimental testing. An added benefit of virtual screening is the creation of numerous databases containing structures with computed chemical and physical properties [\[10–](#page-17-8)[14](#page-17-9)] leading to generative models for discovery of novel molecules and materials [[15](#page-17-10)[–26\]](#page-18-0). Unlike virtual screening where candidates are selected among the structures in the database, generative models have shown a remarkable ability to leverage the database to produce new structures with desirable properties. A notable limitation is a large database and no feedback-loop to improve the generated molecules beyond what is learned from the database. To remedy this, reinforcement learning (RL) methods havestarted to become a competitive alternative [[27](#page-18-1)[–38](#page-18-2)] to methods relying on existing databases. RL involves a model that produces molecules and obtains properties for these molecules, by some external means other than a database. This provides the basis for the model to learn from the molecules it produces.

Whereas generative models rely on databases for pretraining, RL is usually done without any prior knowledge leading to initial inefficiency as basic chemical and physical rules are learned. Instead a reward must be defined, meaning that it requires a setting where a meaningful reward function is available, such as an energy or other things to be optimized.

In this work we build upon a previous RL algorithm called Atomistic Structure Learning Algorithm (ASLA) [\[33](#page-18-3)] by incorporating databases into molecular RL to improve sample efficiency while simultaneously allowing the ML model to learn beyond the knowledge contained in the database. First, a general purpose model is trained using a database to create a model applicable for all stoichiometries. Then, a copy of the general purpose model is created for each stoichiometry of interest. These models are then further refined in a RL setting in a search for low energy isomers for the given stoichiometry. Specifically, we utilize a very small subset of the GDB-11 [\[39\]](#page-18-4) database that consists of small organic molecules satisfying simple chemical stability rules and containing up to 11 atoms of C, N, O and F. We demonstrate that our RL model is able to both replicate structures in the database and produce novel low energy structures. By focusing on low energy structures, we believe we avoid the general pitfall of generative models that may produce a large degree of unsynthesizable molecules, as e.g. shown in the work of Gao and Connor[[40](#page-18-5)]. Unlike previous approaches using SMILES[[41](#page-18-6)] or graphs, we operate directly in Cartesian coordinates thus allowing for optimization of the potential energy hence easily biasing the search towards thermodynamically stable structures. To improve sample-efficiency we take a model-based approach where, similar to[[36](#page-18-7)], the potential energy surface is modeled by a neural network allowing for approximate but cheap optimization. Finally, we introduce an architecture based on SchNet [\[42](#page-18-8)] with a self-attention mechanism [\[43\]](#page-18-9) allowing the RL model to account for long-range effects. The paper is constructed as follows: first the RL theory is outlined, followed by a description of the neural network architecture. Then the database pretraining and RL phase are described before demonstrating the method on a subset of GDB-11. Finally, we apply the method to larger molecules outside the training distribution.

2. Theory

The objective of RL is to solve a decision problem, i.e. formulate a program that given an input can decide on the optimal action. Specifically, we refer to this program as an agent which is given a state, *s*, and must decide on an action, *a*. In the general case the decision process involves multiple steps indexed with the subscript *t* while *T* is used for the final step. In order to solve the problem the agent must device a policy, π , which is a probability distribution over the possible actions in a given state. The optimal policy is the policy which maximizes the sum of rewards, where $r(s)$ is the reward given in state s . The states, actions and rewards are user-specified and describes the problem to be solved. Following[[33](#page-18-3), [34\]](#page-18-10), the state space is defined as all (possibly partial) molecules along with a bag of atoms [\[34\]](#page-18-10) not yet attached to the molecule. For the reward we seek to minimize the potential energy, i.e. we set intermediate rewards to zero and assign a final reward based on the potential energy of the molecule:

$$
r(s_t) = \begin{cases} \max\left(\frac{E_{\text{ref}} - E(s_T)}{\Delta E} + 1, 0\right), & \text{if } t = T \\ 0, & \text{else} \end{cases} \tag{1}
$$

here *E*ref is the lowest energy observed and ∆*E* = 10 eV is the energy span from *E*ref where energy differences are resolved. Note that $E_{\text{ref}} \leqslant E(s_T)$ meaning that $0 \leqslant r(s_t) \leqslant 1$. We scale the reward to stabilize the training as energies of produced structures may fluctuate substantially during the RL phase. We find that the steady lowering of *E*ref during searches caused by the identification of ever better structures constitutes a manageable learning setting. Since the reward function depends on the total energy of the molecule, separate agents must be trained for each stoichiometry of interest. This represents an appealing case for trivial parallelisation over the agents.

To maximize the expected sum of rewards we define the *Q*-value,

$$
Q_{\pi}(s, a) = \mathbb{E}_{\pi} \left[\sum_{k=t+1}^{T} r(s_k) \middle| s_t = s, a_t = a \right]
$$

= $\mathbb{E}_{\pi} [r(s_T) | s_t = s, a_t = a],$ (2)

i.e. the expected final reward when taking action *a* in state *s* and then following policy π . The goal of the agent is to infer the optimal *Q*-value function:

$$
Q_*(s, a) = \max_{\pi} Q_{\pi}(s, a) \,\forall s, a,\tag{3}
$$

Figure 1. Given a state, *s^t* and an action *a^t* , the target *Q*-value is calculated by computing the energy of finished structures involving the state-action pair. In the above case a hydrogen atom is placed, which has led to four different structures. The *Q*-value is updated towards the reward for the lowest energy structure built.

thereby enabling the agent to perform the best action in every state. To improve the *Q*-value function we parameterize it by a neural network and update it as the agent collects new experience. Specifically, we evaluate the *Q*-values on a voxelated grid [\[35\]](#page-18-11), which allows us to update the *Q*-value towards the highest final reward observed by the agent for a specific state-action pair (figure [1](#page-3-0)), which for a deterministic problem puts a lower bound on the optimal *Q*-value [\[44\]](#page-18-12). Additionally, this discretization allows for easy inference of the optimal atom placement by simply finding the voxel which maximizes the *Q*-value.

3. Architecture

The state representation is utilized for calculating the energy of a structure as well as a state value which is used for calculating the *Q*-value, but is independent of the specific action. For improved data efficiency the state and action representation must satisfy symmetries in the Hamiltonian, i.e. translation, rotation and mirroring of the molecule as well as permutation of identical atoms. To incorporate these properties in the state representation we utilize pairwise distances (figure $2(a)$ $2(a)$, **D**), expanded in a Gaussian basis:

$$
\mathbf{D}_{ijk} = e^{-\gamma (r_{ij} - \mu_k)^2} f_c(r_{ij}), \qquad (4)
$$

where $\gamma =$ 1 Å $^{-2}$ and r_{ij} is the distance between atom *i* and *j*, with a total of *n* atoms in the structure. We let *k* be integer values given by $1 \leq k \leq 20$ which corresponds to 20 values for μ_k , uniformly between 0 and a cutoff-radius $r_c = 5$ Å. One can attribute D_{ijk} to encode whether the distance between atom *i* and atom *j* is close to the value given by μ_k . The cutoff function:

$$
f_c(r) = \begin{cases} \frac{1}{2} \left(\cos(\frac{\pi r}{r_c}) + 1 \right), & \text{if } r \leq r_c \\ 0, & \text{else} \end{cases}
$$
 (5)

emphasizes the importance of the local neighborhood by decaying **D***ijk* as a function of *rij* and ensures a smooth transition to zero at r_c . For the atoms, we utilize randomly initialized trainable atom type embeddings (figure [2](#page-4-0)(a), Z_H , Z_C , Z_N). Finally, the bag is represented by the number of remaining atoms (figure [2](#page-4-0)(a), *B*).

The action is represented by distances to atoms already placed (figure [2\(](#page-4-0)a), *DQ*) as well as a special query type embedding (figure [2](#page-4-0)(a), *ZQ*). When calculating *Q*-values the query atom is placed at various voxels allowing for inference of *Q*-values at possible positions of the next atom to be placed. In this way, all the encoded distances are easily converted to a 3D structure.

The state representation (figure $2(b)$ $2(b)$, green) is updated using SchNet-blocks. In the following we will use superscripts to index the blocks, if multiple blocks follow each other. Fully connected layers are given as *Wⁱ* where the full details for each fully connected layer is given in the [appendix.](#page-11-0) Each block operates on the distance and atom type embeddings using continuous-filter convolutions with skip connections as introduced in SchNet:

$$
\tilde{Z}_i^l = Z_i^l + \sum_{j \neq i} Z_j^l \circ W_d^l(\mathbf{D}_{ij}),\tag{6}
$$

where \circ is elementwise-multiplication and $Z_i \in \mathbb{R}^d$ are the atom embeddings. In the present work we set the dimension of the atom representation to $d = 64$. As we will process the atom representation further within block *l*, we use \tilde{Z} to denote the intermediate product. The convolution is followed by an atomwise fully connected layer with a skip connection:

$$
Z_i^{l+1} = \tilde{Z}_i^l + W_a^l(\tilde{Z}_i^l),\tag{7}
$$

which is passed to the next SchNet block. By chaining several blocks, information from distant atoms are passed to each atom representation. After $L = 5$ layers, the atomwise representations, Z_i^L , are used for predicting the energy (*E*) of the structure as combination of local contributions:

$$
E = \sum_{i} W_{E}(Z_{i}^{L}).
$$
\n(8)

Additionally, we compute a state value (*SV*):

$$
SV = W_{SV}\left(W_B(B) \oplus \sum_i Z_i^L\right),\tag{9}
$$

where *⊕* is concatenation. The state value is an indication of whether high or low *Q*-values are expected from the current state, as will be evident in the next section. Unlike the energy, the state value must consider remaining atoms in the bag when calculating if the current state can progress into a valid molecule.

Having covered the part of the architecture that deals with the state, we now turn to the action part given in figure [2\(](#page-4-0)b), purple. The query type representation is updated using only a single SchNet-block in order to keep the computational cost low which is desirable since many actions must be queried in every episode. Furthermore, a multi-head self-attention block over all the atom representations follows. In contrast to local

4

models where information from distant atoms must propagate through several blocks, self-attention allows for immediate global information flow. In the case of predicting *Q*-values for unfinished structures this is especially relevant, as the model must be aware of possible dangling bonds in one end of a molecule while predicting *Q*-values in the other end. For $h = 8$ heads, we calculate a query, key and value as:

$$
q_i^l = Q^l(Z_i), \ k_i^l = K^l(Z_i), \ v_i^l = V^l(Z_i), \tag{10}
$$

where the superscript index the head and Q^l, K^l, V^l are linear projections to a subspace of size $d_h = d/h$, where $Z_i \in \mathbb{R}^d$. From this, a dot-product attention score is calculated:

$$
\alpha_{ij}^l = \frac{\exp\left(q_i^l \cdot k_j^l / \sqrt{d_h}\right)}{\sum_j \exp\left(q_i^l \cdot k_j^l / \sqrt{d_h}\right)},\tag{11}
$$

which indicates the importance of latent representation v_j^l to describe v_i^l . From these scores a new latent representation of Z_Q is created as:

$$
Z_Q^l = \sum_j \alpha_{Qj}^l v_j^l,\tag{12}
$$

which is finally concatenated and processed by a fully connected layer with a skip connection and layer normalization [\[45\]](#page-18-13):

$$
\tilde{Z}_Q = \text{Layer-norm}[Z_Q + W_c(Z_Q^1 \oplus \dots \oplus Z_Q^h)].\tag{13}
$$

The representation of the query atom is then used for calculating the *Q*-value:

$$
A = W_A(\tilde{Z}_Q) \tag{14}
$$

$$
Q = \text{Softmax}(SV + A),\tag{15}
$$

where $A \in \mathbb{R}^{M+1}$, M is the number of atom types, and $SV \in \mathbb{R}$ is added to the first M entries of A . Entry i in *Q* specify the *Q*-value for atom type *i* and the *M* + 1 *′* th entry allows for low *Q*-values for all atom types. *SV* enables the network to lower the *Q*-value for all possible actions in a given state, instead of independently learning that all actions leads to high-energy structures. By evaluating the *Q*-value at multiple voxels, the agent follows the greedy policy of picking the action with the highest *Q*-value, leading to the structure in figure $2(c)$ $2(c)$.

4. Method

The algorithm consists of two phases. In the first phase we use a simple form of imitation learning (IL) called behavioral cloning, where the agent learns to build the structures in the database as well as predicting their energies and forces. This agent serves as a starting point for all agents employed in the next phase.

In the second phase, a RL process is started where stoichiometric-specific agents refines the IL model by constructing new molecules and querying an energy calculator. Based on the received energies and forces, the model updates the *Q*-values, energies and forces before constructing a new molecule. As the agents receive feedback from the energy calculator the molecules continue to improve.

4.1. Imitation learning phase

To create an initial model the GDB-11 database consisting of molecules containing up to 11 heavy atoms (C, N, O, F) is utilized. Specifically, we use all 1850 structures with 6 heavy atoms for supervised pretraining. Using RDKIT[[46\]](#page-18-14) SMILES are transformed into 3D structures and a single point density functional theory (DFT) calculation of the energy and forces is performed using GPAW [\[47,](#page-18-15) [48\]](#page-18-16) using a localized atomic basis set[[49\]](#page-18-17). The model is then trained using the following loss function:

$$
l = \rho_E l_E + \rho_F l_F + \rho_Q l_Q, \tag{16}
$$

where we have:

$$
l_E = ||E - \hat{E}||^2,\t\t(17)
$$

$$
l_F = \frac{1}{3N} \sum_{i=1}^{3N} \text{Huber}(F_i, \hat{F}_i),
$$
 (18)

$$
l_{Q} = -\sum_{i=1}^{M+1} p_{i} \log \hat{Q}_{i},
$$
\n(19)

where the hat denotes values predicted by the network and $\rho_E = 0.1$, $\rho_F = 0.9$ and $\rho_O = 1$ are empirically chosen to balance the contributions to the total loss. *N* is the number of atoms in the structure, with *M* different atom types.

Theenergy (equation (17) (17) (17)) is trained using a mean squared error (MSE) loss while forces (equation (18) (18) (18)) are updated using a Huber loss given by:

Huber
$$
(F, \hat{F}) = \begin{cases} \frac{1}{2}(F - \hat{F})^2, & \text{if } |F - \hat{F}| < 1 \\ |F - \hat{F}| - \frac{1}{2}, & \text{else} \end{cases}
$$
, (20)

i.e. a squared loss for small differences and a linear loss for large errors. The Huber loss was more stable by suppressing the effect of large force outliers which were occasionally present in the structures built by the model.

Similarly, a cross entropy loss for the *Q*-values (equation [\(19\)](#page-6-0)) was found to be more stable than a MSE for the pretraining phase where only Q-values of 0 or 1 are required. For the cross entropy loss \hat{Q}_i refers to the *Q*-value for atom type *i* and we set $p_i = 1$ for the atom type placed in the database and 0 for the other types. Additionally, for each action present in the database we generate five perturbed actions by randomly moving the selected atom and setting $p_i = 1$ for the $M + 1'$ th entry in the *Q*-value prediction, thereby enforcing *Q*-values for all atom types to be zero for the randomly generated actions. As this generates an imbalance in the training data the valid actions are weighted by a factor of five.

The model is implemented in Pytorch [\[50](#page-18-18)] and trained using the Adam[[51](#page-18-19)] optimizer with an initial learning rate of ⁵ *[×]* ¹⁰*−*³ and a batch size of 384. We use 90% of the structures for training the remaining 10% are used as a validation set for decaying the learning rate by a factor of 2 when the validation error plateaus for 30 epochs. Once the learning rate decayed below 10*−*⁶ the validation loss stagnated, and the final model is chosen for employment in the RL phase.

4.2. Reinforcement learning phase

In the RL phase we deploy the single IL model for all 135 stoichiometries present in the training set. A cubic cell of dimension [20 Å, 20 Å, 20 Å] and a *Q*-value grid resolution of 0.2 Å is chosen, with the initial atom restricted to the center of the cell. We use a modified *ε*-greedy strategy, to trade-off exploration and exploitation. To satisfy two random moves per episode in expectation, we choose a greedy action with probability 1-2/T and a random action with probability 2/T, where *T* is the number of atoms in the structure. We choose 5% of random actions uniformly random, while the other 95% are uniformly sampled from the top 5% of actions. Furthermore, all hydrogen atoms are masked until all other atom types are placed which reduces the action space without excluding any molecules. Due to the IL model an action among the highest *Q*-values is frequently taken which ensures exploration while simultaneously suppressing the large fraction of actions resulting in completely invalid molecules.

To limit the action space, we only allow actions which fulfill:

$$
c_1[r_{cov}(a) + r_{cov}(i)] < r_{ai} < c_2[r_{cov}(a) + r_{cov}(i)],\tag{21}
$$

for at least one atom *i* already present in the structure. Here $c_1 = 0.75$, $c_2 = 1.25$ and $r_{cov}(i)$ is the covalent radius of atom *i*. $r_{\text{cov}}(a)$ is the covalent radius of the atom placed in action *a* and r_{ai} is the distance between the new atom and a present atom *i*. That is, the new atom must be placed within 0.75–1.25 times the sum of the covalent radii of itself and an already present atom. This restricts the model to building non-fragmented structures for a better comparison with the database.

The agent trained as detailed in the previous section is perfectly capable of building a variety of different molecules given a predetermined stoichiometry. Owing to the stochastic nature of the modified *ε*-greedy policy employed sequential builds using the same agent results in different structures being built.

We exploit that to construct a first ensemble of structures by tasking the agent with building molecules 200 times. It does so according to the pretrained *Q*-values and every completed structure is subject to a

relaxationin the model energy, equation (8) (8) , followed by snapping the molecule back on the grid. If the relaxation results in a fragmentation of the molecule into several pieces, the original structure is used instead. The initial exploration phase promotes exploration of a large part of configuration space to avoid premature convergence to a local minimum. Since the model is pretrained the generated molecules will generally be of high quality.

Once the first 200 builds are completed, the search enters the RL mode. Here the algorithm alternates between generating a structure and updating the model using five mini-batches until a total of 600 additional molecules have been generated, which fine-tunes the agent for each specific stoichiometry. For the *Q*-values theloss function is changed to MSE, since the target is now given by equation (2) (2) (2) , i.e. it is no longer 0 or 1, but depends on the potential energy of the molecule. By further improving the *Q*-values and force-predictions the search is directed towards low-energy regions of configuration space.

4.3. GDB-11 benchmark

We start by testing the performance of the current framework when it comes to identifying molecules with stoichiometries already present in the database used for the training. The search is conducted as a set of 64 independent restarts following the outlined protocol: using the data-based-trained agent for 200 builds and applying RL for 600 subsequent builds. To facilitate the quantification of the amount of new structures found, we resort to the use of SMILES, as an analytic tool. We stress that SMILES are not used in any way by the agents as this would limit the scope of these. Once the search is finished all structures are post processed by taking five gradient steps using the *final* model energy landscape. This is a computationally cheap step that removes uncertainties from the original relaxation of the molecules in the less reliable model energy landscape that had been learned up to the point of the RL generating the particular molecule as well as unfortunate grid snapping. These post processed structures are then converted to SMILES and all unique constitutional isomers are found. To this end, we show in figure [3](#page-7-0) some of the molecules being built when searching for $C_4H_4O_2$. As illustrated, we find both new constitutional isomers and often several stereoisomers for these. Looking across these 64 restarts, all of the structures of this composition present in the database (orange arrow) are found again (purple bar). However, also a considerable number of molecules not present in the database are found (green bar).

To investigate whether the produced molecules are of low energy we illustrate the evolution of the 64 agents from episode 400 to 800 in figure [4](#page-8-0). The histograms indicate the energy distribution of the structures built in the given episode across the 64 agents. As the search progresses the distribution shifts towards lower energies as the model begins converging, which is further evident by the mean of the distribution (red line) shifting down. Similarly, when we only consider the mean of the lowest energy structure in each run (i.e. not necessarily built in episode 400 or 800), which is depicted using dark red we see a similar shift. In blue, the average energy of the structures in the database, snapped to the grid ASLA operates on, is given. Initially the database is better than the average built of the agent due to imperfect fitting to the database but is overtaken by the agent at episode 800. If one looks only at the best structure in the database (dark blue) the average lowest energy approaches this limit and is marginally beaten by one of the isomers (dark red, dashed). Fully

relaxing all unique isomers in DFT indeed reveals that the lowest energy isomer produced by ASLA coincides with the minimum structure in the database.

To observe the decision process for the RL algorithm we plot the *Q*-values for one of the runs in figure [5.](#page-8-1) First of all, the model has clearly learned a great deal about chemical bonding and thus generally suppresses invalid actions, predicting only high *Q*-values for sensible bonding sites. The agent is fully aware of possible symmetries during the build. Starting with a single atom in *s*1, the *Q*-values have spherical symmetry. For the linear dimer in s_2 the symmetry of the *Q*-values reduces to a ring, and for the Y-shaped C_3O backbone in s_5 , two symmetric 'caps' of high *Q* values develop. As evident in states s_4-s_8 where multiple sites have high *Q*-values, the model decides between different possible isomers when building the molecule. Bond lengths chosen early on e.g. the C–C bond lengths when placing the C atoms from s_2 to s_5 have an impact on later *Q*-values. The *Q*-values encircled by a black ellipse in s_8 are thus smaller than the *Q*-value that are chosen upon building *s*9. In both cases, aldehyde (HOC-) groups are formed, but at *C* atoms involved in double or single C–C bonds, respectively, the latter being the energetically preferred. Placing H atoms at both sites would have been possible causing tautomerization involving the methyl group, but again given the initial choices for C–C bond lengths, this is no longer preferable as reflected by the *Q*-values in *s*9. Owing to the modified *ε*-greedy policy, such alternative molecular builds are occasionally made despite the C–C bond lengths, and the subsequent relaxation in the on-the-fly learned model will provide properly adjusted molecules for the RL training.

In figure [6](#page-9-0) the total number of structures found after 800 episodes for the 15 stoichiometries with most isomers in the database are shown. For a figure involving all 135 stoichiometries, see figure [A1](#page-13-0) in the [appendix](#page-11-0). Similarly to earlier, purple bars indicate the structures present in both the search and the database, whereas green indicate novel structures. A majority of the structures in the database (orange line) are found within the 800 episodes using 64 searches. In total 1769 of the 1850 molecules in the database are found, i.e. slightly more than the 1665 structures used for the training set. Accounting for both novel molecules and structures rediscovered from the database, 20 074 unique constitutional isomers are generated resulting in a 10-fold increase of the database. Especially for stoichiometries where multiple bond combinations are

possible, i.e. for stoichiometries containing a lot of carbon, oxygen and nitrogen several new constitutional isomers are discovered, whereas for hydrocarbons and C*x*H*y*F*^z* where a lot of single bonds are present the database covers a large fraction of the isomers.

If the RL is neglected and the IL model is used for sampling in all 800 episodes, 1649 of the structures in the database and 15 709 novel molecules are generated for a total of 17 358 unique constitutional isomers. The IL model thus covers a large fraction of the produced structures and turning on RL provides 15.6% more molecules.

To illustrate the difference between the IL model and the RL version, we plot the average atomization energy per atom of the structures generated by ASLA throughout the 800 episodes (figure [7\)](#page-9-1) and compare it to the energies of the structures in the database when placed on the same 0.2 Å resolution grid. For each ASLA curve the average is over the 64 independents run as earlier and now also the 135 stoichiometries. As previously observed, the model trained on the database starts out by producing higher energy structures (red curve) than the average structure in the database (blue curve), due to the imperfect fitting of the database. Similarly, the average of the best structures (dark red) is worse than the lowest energy isomer in the database (dark blue). At around 500 episodes both the average and best structures produced by ASLA marginally outperforms the database. At 800 episodes the best structure is outperformed by 0.04 eV/atom on average. If

one only looks at the best structure in each of the 64 runs (dark red, dashed) the database is outperformed by 0.09 eV/atom.

In order to check if this energy difference amounts to new low energy structures the specific *stereoisomers* in the database and the structures generated by ASLA are compared. In that case 1742 of the molecules in the database are found. When counting *constitutional* isomers as in figure [6,](#page-9-0) 1769 of the structures in the database were found, which means that in 27 cases the stereoisomer in the database is not found, but the constitutional isomer is. In total, 29 016 stereoisomers not present in the database are found. Each stereoisomer in both the database and generated by ASLA is then fully relaxed using DFT, which shows that for each stoichiometry the lowest energy stereoisomer in the database is found by ASLA for all but one stoichiometry and in 72 of 135 stoichiometries a lower energy stereoisomer is found. It is necessary that both the IL and the RL phases are present, as the IL agent alone will miss some low energy structures whereas as a pure RL procedure will be significantly delayed before discovering the most favourable configurations, see figures [A4](#page-16-0) and [A5](#page-17-11) in the [appendix](#page-11-0).

4.4. Exploration beyond the database

Having shown that the ASLA framework is capable of reproducing and expanding molecular structures of compositions already present in the database, we now move to explore its performance when applied outside the realms of the database.

As an example, we investigate $C_9H_8O_4$, a molecule with twice as many heavy elements as in the training set. As before, 64 independent runs are started.

In figure [8](#page-10-0)(a) the number of unique constitutional isomers generated as a function of episode number for the IL model (blue) and the model with RL (red) is seen. Unlike for the smaller molecules in IV. C where the IL model was sufficient to cover a large fraction of configuration space there is now a significant difference between the RL and IL agent. The RL model clearly outperforms the IL model in terms of number of molecules generated as the search progresses, showing that the on-the-fly training is able to correct inefficiencies in the initial version. However, the ultimate goal is to generate low energy molecules. Hence, in figure [8](#page-10-0)(b) the atomization-energy-density of the generated molecules for both the IL model and the RL version is seen. As before all stereoisomers are fully relaxed using DFT. The molecules generated by the RL-enhanced model are significantly more stable than the IL model, with an average energy difference of 0.105 eV/atom or 2.22 eV per structure. Thus, the RL version does not only cover more of configuration space, it is also able to focus on the low energy regions. In figure [9](#page-11-1) we investigate a 2D visualization of the generated molecules for both the IL model (squares colored grey to blue) and RL version (circles colored grey to red). The structures are represented using smooth overlap of atomic positions[[52](#page-18-20)] (SOAP) in a 2D space using t-SNE and colored by their energy using two different color schemes to help guide the eye. The 30 lowest energy structures found for both models are framed in black and can be seen figures [A2](#page-14-0) and [A3](#page-15-0) in the [appendix](#page-11-0). The RL version discovers certain low energy regions such as compact aromatic molecules as shown in the inset. The IL version, however, is not able to extrapolate into this region based on what it has learned from the database. Interesting molecules among the low energy isomers include the lowest energy isomer found by the search (red star) as well as the second lowest isomer (see [appendix](#page-11-0)) that both resemble uvitic

10

acid. The search discovers umbellic acid (red square) and caffeic acid (just outside top 30). Additionally, the RL model discovers a stable isomer with a 7-membered ring [\(appendix](#page-11-0)), a substructure not present in the original database as only molecules with up to 6 heavy atoms were used. Despite this, the RL model learns to construct such molecules which would have been hard to discover by a pure supervised generative approach.

For the IL model we observe fewer of the common aromatic molecules as it has no driving force towards low energy regions of configuration space, as exemplified by the lowest energy isomer found (blue star) being 2 eV higher in energy than the corresponding lowest energy structure in the RL version. The missing focus on low energy parts of configuration space results in the 30 lowest energy structures being scattered across the 2D space, mostly composed of elongated structures (such as the blue square) where subparts, unlike large aromatic rings, are more dominant in the GDB-11 database. Utilizing the feedback from the RL is thus crucial to correct flaws in the IL model as well as expanding beyond knowledge in the database.

5. Conclusion

We have presented a framework for autonomous construction of molecules. The method relies on a preexisting database which via supervised learning provides a base level for a model used for constructing new molecules. Further training of the model is done in a RL setting where feedback is provided via single point energy calculations by a high-level quantum mechanical total energy method. The resulting model is able to reproduce structures in the database as well as producing novel structures. The introduced model is able to operate directly in 3D space allowing for biasing the search towards stable molecules. When applying the IL model in domains far from the training set, the RL procedure corrects initial shortcomings in the model. Further work in this direction could investigate building molecules in specific environments, such as organic light-emitting diode or organic solar panels where properties such as HOMO-LUMO gap could be included in the reward function together with the stability.

Data availability statement

The data that supports the findings of this study are openly available at the following URL: <https://gitlab.au.dk/au143309/data-for-imitation-and-reinforcement-project>.

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Table A1. Dimension of data as it passes through the fully connected layers. The activation function is the shifted softplus indicated by ssp.

Bag representation	W_B	$(5, 16,$ spp, 32)
Atomwise layers	W_a	$(64, 64, \text{ssp})$
Distances representation	W_d	$(20, 64, \text{ssp})$
State value	W_{SA}	$(96, 32, \text{ssp}, 1)$
Advantage	W_A	$(96, 32, \text{ssp}, 6)$
Energy	W_F	$(64, 32, \text{ssp}, 16, \text{ssp}, 8, \text{ssp}, 1)$
Concatenation layer	W_c	(64, 64)

Appendix

Network details

In table [A1](#page-12-0) a detailed overview of the blocks in the network is given. The activation function is a shifted softplus[[42](#page-18-8)] (ssp) given by

$$
ssp(x) = \ln(0.5e^x + 0.5)
$$
 (22)

13

Figure A3. 30 lowest energy structures for the IL run. Energies are relative to the lowest energy isomer found in the RL version.

using only the imitation learning agent, using reinforcement agents without any imitation learning, and using reinforcement learning agents that start from the imitation learning agent as described in main text. The depicted molecules are exemplify structures at different places in the histogram.

using only the imitation learning agent, using reinforcement agents without any imitation learning, and using reinforcement learning agents that start from the imitation learning agent as described in main text. The depicted molecules exemplify the structures at different places in the histogram.

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